Amendments to the Claims:

This listing of claims will replace all prior versions, and listings of claims in the application:

Listing of Claims:

1-40. (canceled)

41. (currently amended) A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional <u>user-specified</u> basis function including overlapping portions <u>that are disposed at a plurality of locations and overlap with one another</u> to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional <u>user-specified</u> basis function to obtain a distribution of the overlapping portions <u>that are disposed at the plurality of locations</u>, each overlapping portion representing a two-dimensional treatment portion to be applied to a tissue and combined with other overlapping portions to achieve the three-dimensional target profile for treatment of the tissue according to the distribution obtained from the fitting.

- 42. (original) The method of claim 41 wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented radially from an axis of symmetry and extending in a generally circular treatment pattern around the axis.
- 43. (currently amended) [[The method of claim 42]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the three-dimensional profile has symmetry with respect to a twodimensional section oriented radially from an axis of symmetry and extending in a generally circular treatment pattern around the axis;

wherein the overlapping portions are generally circular, and the two-dimensional basis function comprises discrete basis functions each representing a coverage angle of one of the overlapping portions as a function of a distance from the axis of symmetry.

- 44. (original) The method of claim 41 wherein the three-dimensional profile has symmetry with respect to a two-dimensional section oriented normal across a generally straight treatment pattern.
- 45. (currently amended) [[The method of claim 44]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the three-dimensional profile has symmetry with respect to a twodimensional section oriented normal across a generally straight treatment pattern;

wherein the overlapping portions are generally circular, and the two-dimensional basis function comprises discrete basis functions each representing a depth of one of the overlapping portions as a function of a distance from the axis of symmetry.

46-56. (canceled)

- 57. (currently amended) The method of claim 41 wherein the basis function includes M discrete basis functions representing M overlapping portions.
- 58. (currently amended) [[The method of claim 57]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the basis function includes M discrete basis functions representing M overlapping portions;

wherein the M discrete basis functions represent M overlapping portions across a treatment zone length representing the length across a generally two-dimensional section which is oriented normal across a generally straight treatment pattern or which is oriented radially across a generally circular treatment pattern.

- 59. (previously presented) The method of claim 58 wherein the overlapping portions are generally circular and have a generally uniform energy profile.
 - 60. (previously presented) The method of claim 59 wherein
- (A) for a treatment profile having a generally uniform two-dimensional section oriented normal across a generally straight treatment pattern, the discrete basis functions represent the two-dimensional section as

$$X_i(x_j) = y_i(x_j) = \sqrt{(s/2)^2 - (x_j - x_{0i})^2}$$
 or

(B) for a treatment profile having a generally uniform two-dimensional section oriented radially across a generally circular treatment pattern, the discrete basis functions represent the two-dimensional section as

$$X_i(x_j) = \theta_i(x_j) = \cos^{-1} \left(\frac{x_j^2 + x_{0i}^2 - (s/2)^2}{2 \cdot x_{0i} \cdot x_j} \right)$$

where

s is the diameter of the overlapping portion;

$$j = 1,...,N;$$

 x_j is a reference x-coordinate for the two-dimensional section measured from an optical axis of the cornea of a jth evaluation point for the center of the overlapping portion;

 x_{0i} is an x-coordinate for a center of an ith overlapping portion;

$$(x_{0i} - s/2) \le x_i \le (x_{0i} + s/2);$$

 $y_i(x_j)$ is a depth of the ith basis function for the generally straight treatment pattern;

 $\theta_i(x_i)$ is a coverage angle of the ith basis function for the generally circular treatment pattern.

61. (previously presented) The method of claim 60 wherein x_{0i} is specified for M number of equally spaced overlapping portions as $x_{0i} = i * [(L - s + e) / M]$,

where

and

L is the treatment zone length;

e is an extended zone; and

$$i = 1,...,M$$
.

62. (previously presented) The method of claim 61 wherein e is set to about 0.1 to about 0.5 mm.

63. (currently amended) [[The method of claim 57]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the basis function includes M discrete basis functions representing M overlapping portions;

wherein M is equal to about 7 to about 97.

64. (currently amended) The method of claim 57 further comprising A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis

function to obtain a distribution of the overlapping portions, wherein the basis function includes

M discrete basis functions representing M overlapping portions; and

refitting the target function with the basis function by varying the number of overlapping portions M to iterate for a best fit.

65. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function is:

(A) for myopia and myopic cylinder,

$$f(x_j) = \sqrt{R_1^2 - x_j^2} - \sqrt{\left(\frac{R_1(n-1)}{n-1 + R_1D}\right) - x_j^2} + C$$
 or

(B) for hyperopia and hyperopic cylinder,

$$f(x_j) = R_1 - \frac{R_1(n-1)}{n-1+R_1D} - \sqrt{R_1^2 - x_j^2} + \sqrt{\left(\frac{R_1(n-1)}{n-1+R_1D}\right) - x_j^2}$$
 or

(C) for phototherapeutic keratectomy,

$$f(x_i) = d;$$

where

$$0 \le x_j \le (L - shift);$$

$$j = 0, 1, ..., N-1;$$

$$C = \sqrt{R_1^2 - s^2 / 4} + \sqrt{\left(\frac{R_1(n-1)}{n-1 + R_1D}\right) - s^2 / 4};$$

 x_j is an x-coordinate measured from an optical axis of the cornea of the jth evaluation point for the center of the overlapping portion;

s is the diameter of the overlapping portion;

 R_I is the anterior radius of curvature of the cornea in meters;

 R_2 is the final anterior radius of curvature of the cornea in meters;

n = 1.377 is the index of refraction of the cornea;

D is the lens power of the overlapping portion in diopters;

L is the treatment zone length representing the length across a generally uniform section which is oriented normal across a generally straight treatment pattern for myopic or hyperopic cylinders, or which is oriented radially across a generally circular treatment pattern for myopia or hyperopia;

shift is the amount of emphasis shift; and d is a constant depth.

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- 66. (previously presented) The method of claim 65 wherein the shift is about 0 to about 0.2.
- 67. (previously presented) The method of claim 65 wherein $x_j = j * [(L shift) / N].$
- 68. (previously presented) The method of claim 65 wherein the basis function includes M discrete basis functions representing M overlapping portions, and wherein fitting the target function with the basis function comprises solving the following equation for coefficients a_i representing treatment depth for the ith overlapping portion:

$$f(x_j) = \sum_{i=1}^{M} a_i X_i(x_j)$$

where

 $X_i(x_j)$ is the ith basis function; and

i = 1, ..., M.

69. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein fitting the target function and the basis function comprises specifying a deviation for each of the N discrete evaluation points.

70. (previously presented) The method of claim 69 further comprising refitting the target function with the basis function by varying the deviations to iterate for a best fit.

71. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein fitting the target function and the basis function comprises evaluating closeness of the fit and repeating the fitting step if the closeness does not fall within a target closeness.

72. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function and the basis function are fitted using a least square fit.

73. (currently amended) The method of claim 41 further comprising A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and

refitting the target function with the basis function by varying the size of at least one of the overlapping portions to iterate for a best fit.

74. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the overlapping portions have different sizes.

75. (currently amended) [[The method of claim 41]] A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern; and

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions;

wherein the target function and the basis function are fitted using a simulated annealing process.

76. (currently amended) The method of claim 41 further comprising A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and

specifying a merit function representing an error of fit between the target function and the basis function; and minimizing the merit function.

77. (currently amended) The method of claim 41 further comprising A method for fitting a three-dimensional target profile, the method comprising:

providing a two-dimensional basis function including overlapping portions to represent a three-dimensional profile which has symmetry with respect to a two-dimensional section extending along a treatment pattern;

fitting the three-dimensional target profile with the two-dimensional basis function to obtain a distribution of the overlapping portions; and

refitting the target function with the basis function by selecting an overlapping portion location and varying the characteristics of the overlapping portion at the selected location to iterate for a best fit.